### SIMON FRASER UNIVERSITY



# CVPR is a contemporary art exhibition -- Garbage is a source for impact --

3D Scene Understanding for Vision, Graphics, and Robotics Workshop @ CVPR2020

Yasutaka Furukawa

### We are scared of reviewers...





# CVPR is a contemporary art exhibition -- Garbage is a source for impact --

#### 3D Scene Understanding for Vision, Graphics, and Robotics

CVPR 2020 Workshop, Virtual, June 15th, 2020





#### News

Due to the pandemic, our workshop will totally be virtual this year. We will host an online chat room for communication with the speakers and Q&A. The details are coming soon. Looking forward to meet you online!.

Invited talks and oral presentations will be presented live or by recorded videos in the same Zoom room, all of the talks will have live Q&A session, please refer to the Program for recorded videos and more details.

#### **Invited Speakers**







Kristen Grauman (UT Austin)

Sergey Levine (UC Berkeley)

Andreas Geiger (University of Tübingen)







Yasutaka Furukawa (Simon Fraser University)

Daniel Ritchie (Brown University)

Jeannette Bohg (Stanford University)







Shuran Song (Columbia University)

Andrea Tagliasacchi (Google Brain)

Katerina Fragkiadaki (Carnegie Mellon University)

#### **Opening Remark**



David Forsyth (University of Illinois Urbana-Champaign)

#### ScanNet Indoor Scene Understanding Challenge CVPR 2020 Workshop, Seattle, WA

June 19, 2020



#### Introduction

3D scene understanding for indoor environments is becoming an increasingly important area. Application domains such as augmented and virtual reality, computational photography, interior design, and autonomous mobile robots all require a deep understanding of 3D interior spaces, the semantics of objects that are present, and their relative configurations in 3D space.

We present the first comprehensive challenge for 3D scene understanding of entire rooms at the object instance-level with 5 tasks based on the ScanNet dataset. The ScanNet dataset is a large-scale semantically annotated dataset of 3D mesh reconstructions of interior spaces (approx. 1500 rooms and 2.5 million RGB-D frames). It is used by more than 480 research groups to develop and benchmark state-of-the-art approaches in semantic scene understanding. A key goal of this challenge is to compare state-of-the-art approaches operating on image data (including RGB-D) with approaches operating directly on 3D data (point cloud, or surface mesh representations). Additionally, we pose both object category label prediction (commonly referred to as semantic segmentation), and instance-level object recognition (object instance prediction and category label prediction). We propose five tasks that cover this space:

- 2D semantic label prediction: prediction of object category labels from 2D image representation
- 2D semantic instance prediction; prediction of object instance and category labels from 2D image representation
- 3D semantic label prediction: prediction of object category labels from 3D representation
- 3D semantic instance prediction: prediction of object instance and category labels from 3D representation
- Scene type classification: classification of entire 3D room into a scene type

For each task, challenge participants are provided with prepared training, validation, and test datasets, and automated evaluation scripts. In addition to the public train-val-test split, benchmarking is done on a hidden test set whose raw data can be downloaded without annotations; in order to participate in the benchmark, the predictions on the hidden test set are uploaded to the evaluation server, where they are evaluated. Submission is restricted to submissions every two weeks to avoid finetuning on the test dataset. See more details at http://kaldir.vo.in.tum.de/scannet\_benchmark/documentation if you would like to participate in the challenge. The evaluation server leaderboard is live at http://kaldir.vo.in.tum.de/scannet\_benchmark/.

CAD model
Structured geometry
Semantically segmented geometry

Model editing

texture/normal/bump/effects mapping

Physics simulations

Interactions (VR/AR)

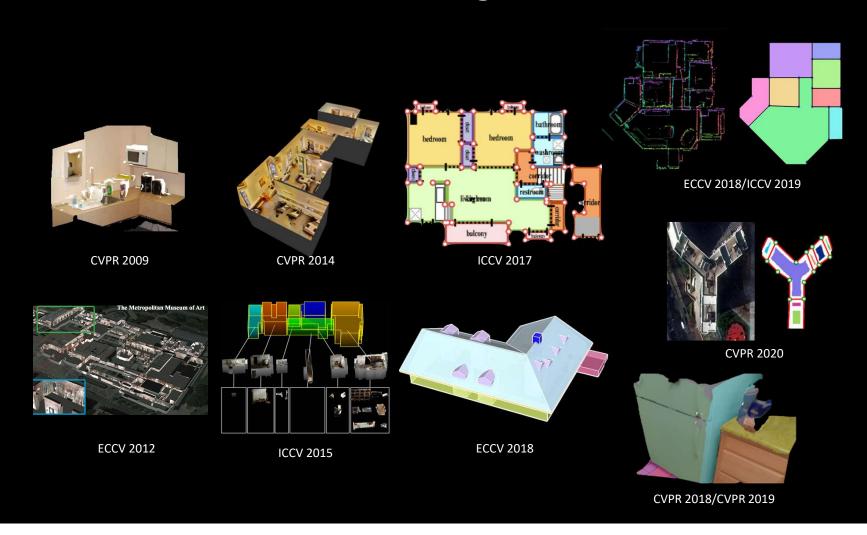
• Architectural analysis

• ...

[Transformer]



### **Structured Geometry Reconstruction**





#### Ice-age

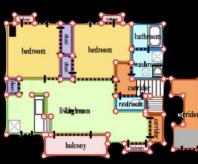
#### Revolution



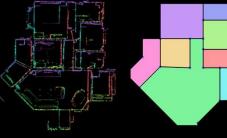
CVPR 2009



**CVPR 2014** 



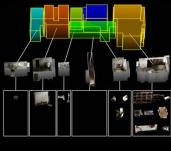
ICCV 2017



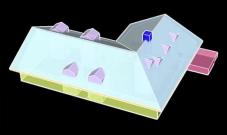
ECCV 2018/ICCV 2019



ECCV 2012



ICCV 2015



ECCV 2018



CVPR 2020



CVPR 2018/CVPR 2019

#### Ice-age (no impact)

#### **Revolution (impact)**



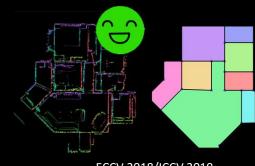
CVPR 2009



**CVPR 2014** 



CVPR 2018/CVPR 2019



ECCV 2018/ICCV 2019



ECCV 2012



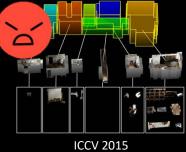
ECCV 2018



CVPR 2020



ICCV 2017





I've posted a new essay here which is the product of my recent attempts to better understand contemporary art. There are some pretty fundamental things here that I didn't get from any of the books that I read on this topic, nor from my undergraduate art degree. I'm really grateful to Jason Salavon for all his time spent discussing this with me.



AARONHERTZMANN.COM

#### What is contemporary art?

I recently had some private conversations with artists that changed how I understand contemp...

Like · Reply · 4d



Aaron Hertzmann replied · 1 Reply



#### Alyosha Efros

I like the comparison to scientific communities. Another commonality is that, just like 90% of CVPR papers will turn out to be junk (either immediately or after a few years), so is 90% of contemporary art. This is normal and we shouldn't be disturbed by it. Just as I am happy to find a few CVPR papers that I like, I should feel happy if, at any contemporary art exhibition, I find 1-2 pieces that speak to me.

Like · Reply · 4d





#### Aaron Hertzmann

https://en.wikipedia.org/wiki/Sturgeon%27s\_law

**EN.WIKIPEDIA.ORG** 



Sturgeon's law - Wikipedia



Like · Reply · 4d

Like · Reply · 4d



Aaron Hertzmann replied · 1 Reply



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Aaron Hertzmann

https://en.wikipedia.org/wiki/Sturgeon%27s\_law

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Sturgeon's law - Wikipedia

Like · Reply · 4d

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1 2

Like · Reply · 4d



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Like · Reply · 4d





**Aaron Hertzmann** 

https://en.wikipedia.org/wiki/Sturgeon%27s\_law

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Sturgeon's law - Wikipedia

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#### Sturgeon's law

From Wikipedia, the free encyclopedia

Sturgeon's law (or Sturgeon's revelation), is an adage that states that "ninety percent of everything is crap." The adage was coined by Theodore Sturgeon, an American science fiction author and critic. The adage was inspired by Sturgeon's observation while science fiction was often derided for its low quality by critics, the majority of examples of works in other fields could equally be seen to be of low quality, and science fiction was thus no different in that regard from other art.

Some make a distinction between the revelation ("ninety percent of everything is crap") and the law ("nothing is always absolutely so").

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### CVPR is a contemporary art exhibition

Let's stop pretending that all our 2000 CVPR papers convey good ideas

Garbage is a source for impact

### We are scared of reviewers...





#### Ice-age (no impact)

#### **Revolution (impact)**



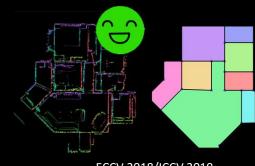
CVPR 2009



**CVPR 2014** 



CVPR 2018/CVPR 2019



ECCV 2018/ICCV 2019



ECCV 2012



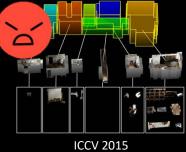
ECCV 2018

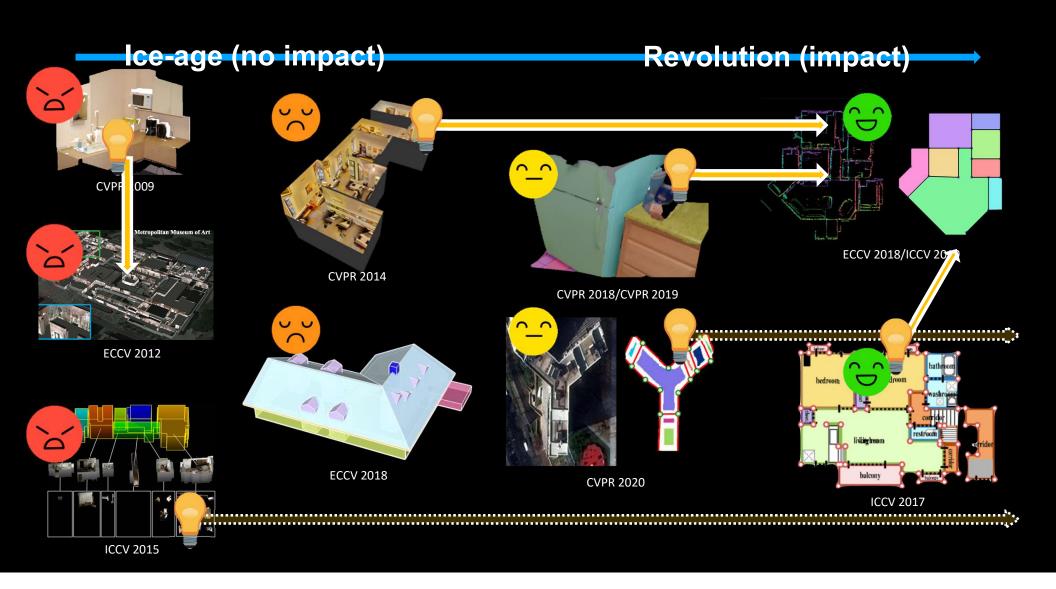


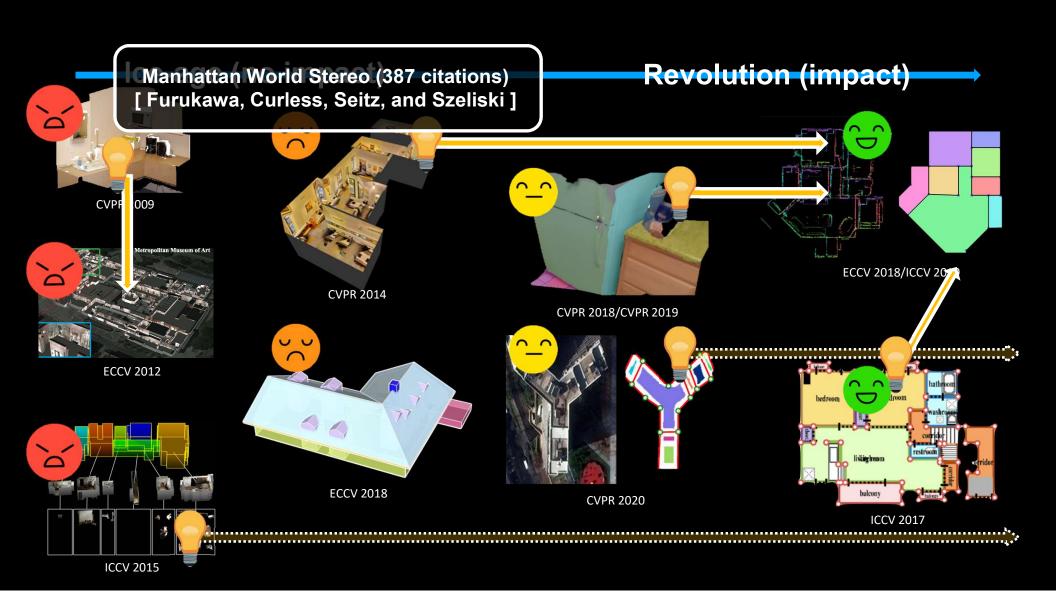
CVPR 2020

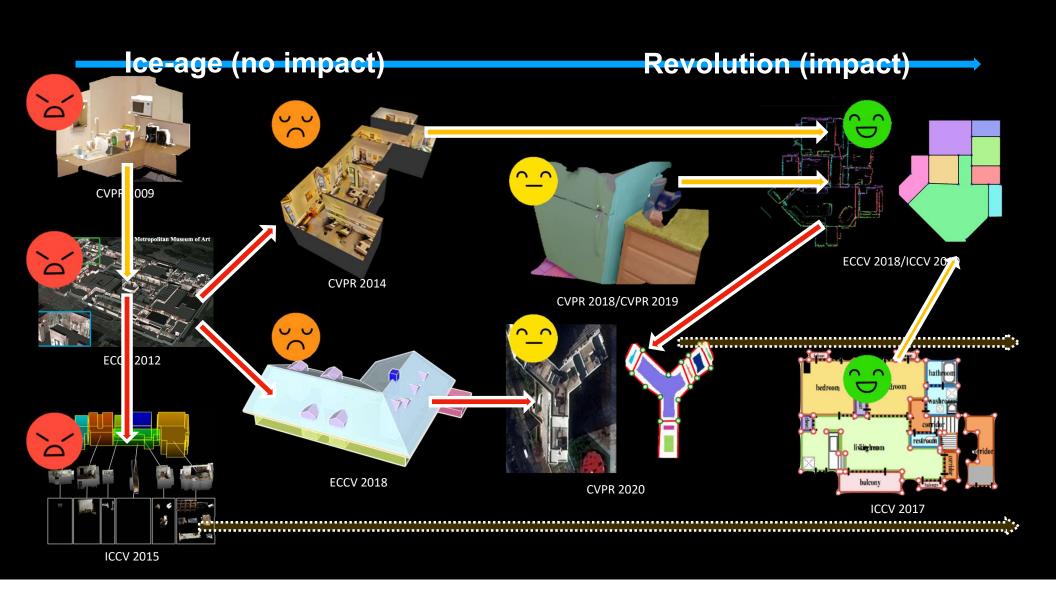


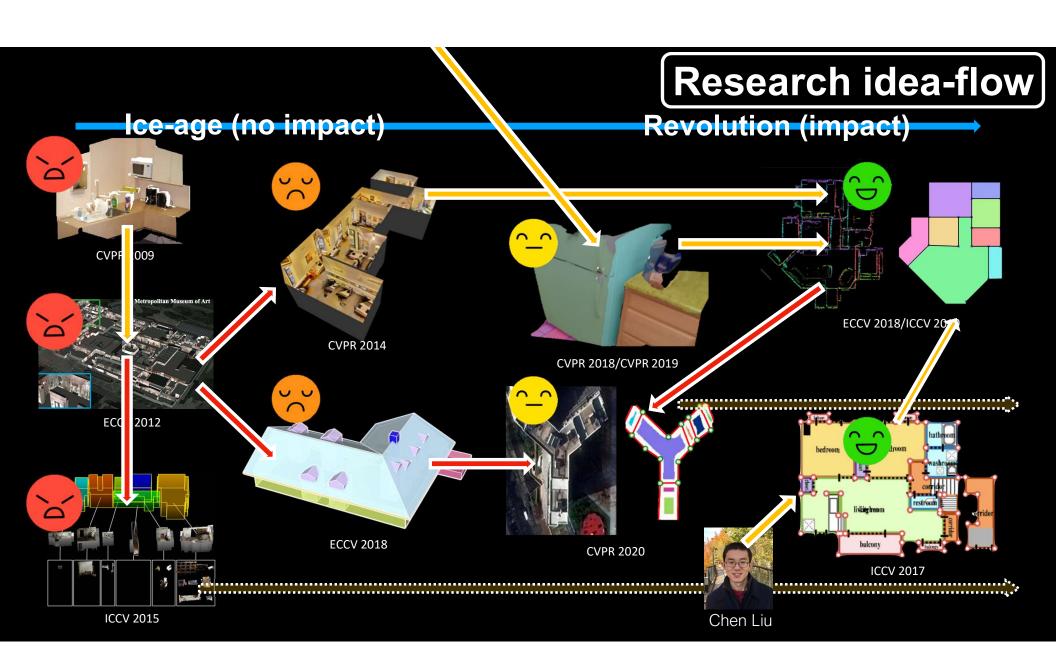
ICCV 2017

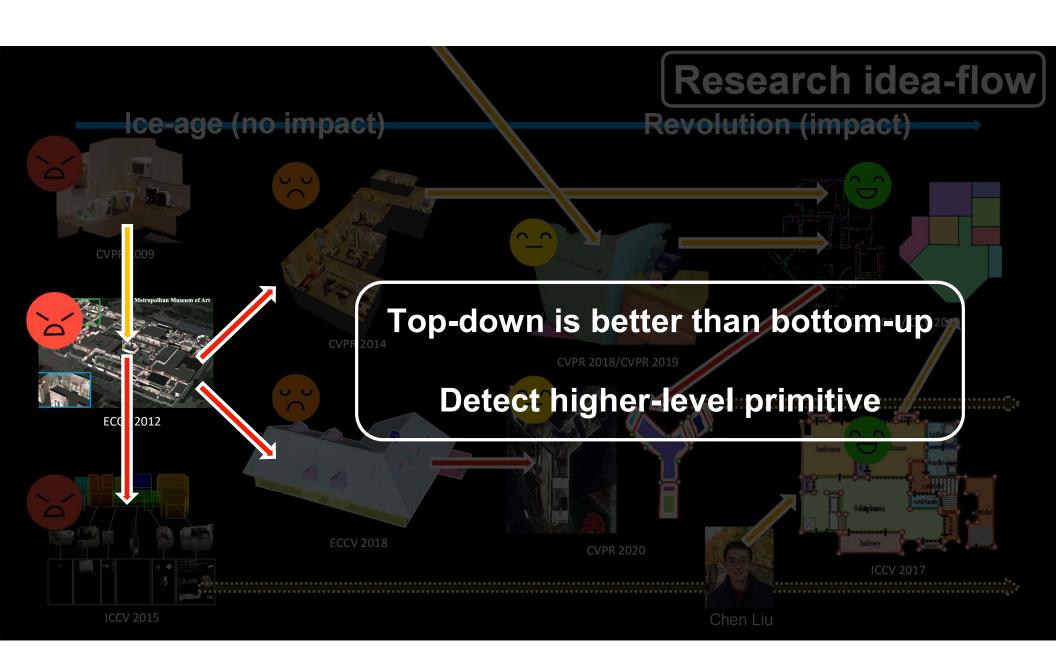




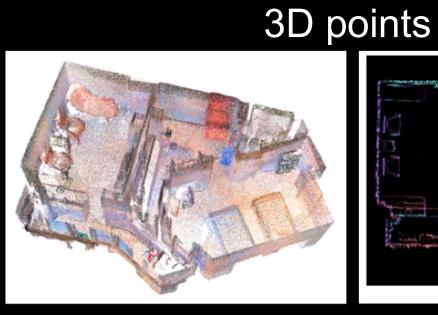


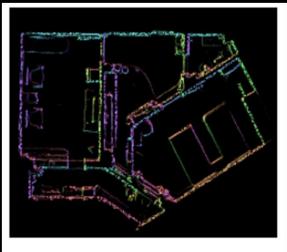


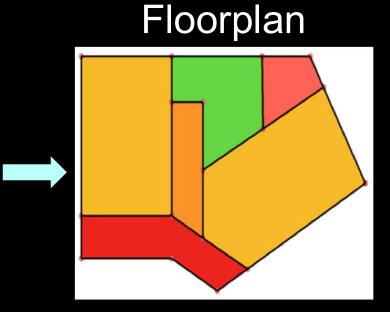




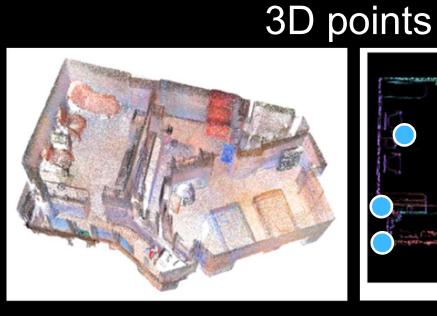
## Detect higher-level primitives



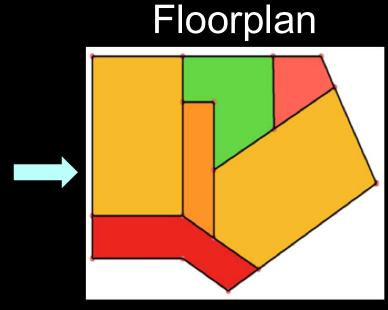




### Bottom-up: Corner Detection

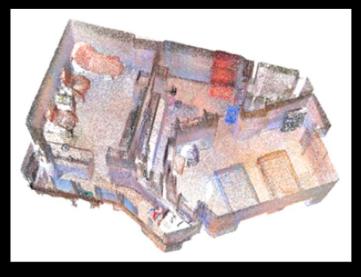


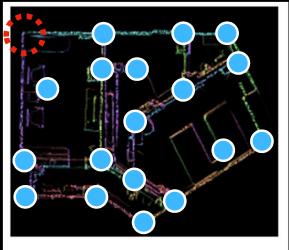


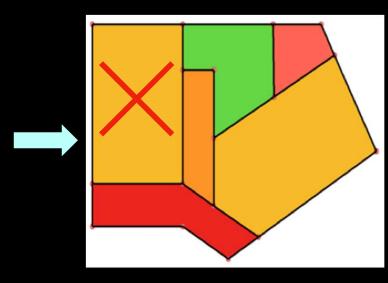


## Bottom-up: Corner Detection

One missing corner

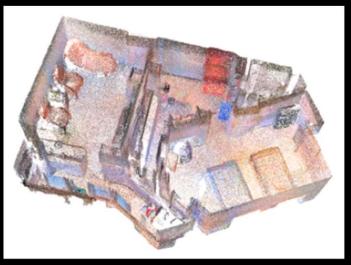




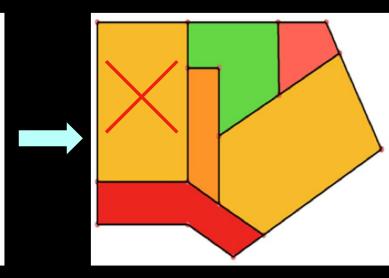


### Bottom-up: Corner Detection

One missing corner

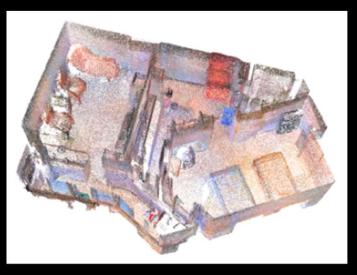




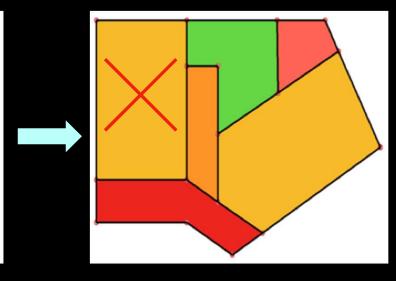


- 1. Cannot miss a single primitive.
- 2. Enumerate much more than necessary.
- 3. # of primitives to enumerate grow exponentially as the primitive DoF grows.

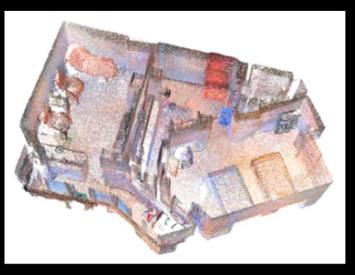
## Top-down: Region Detection

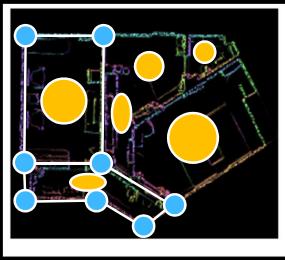


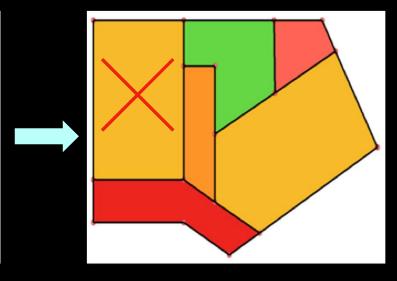


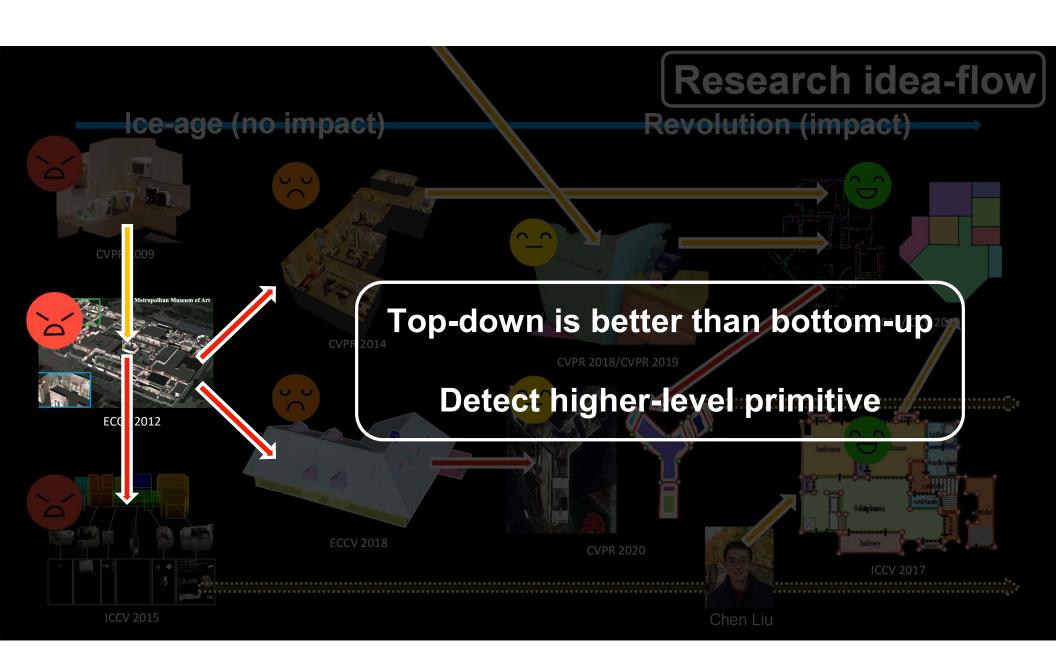


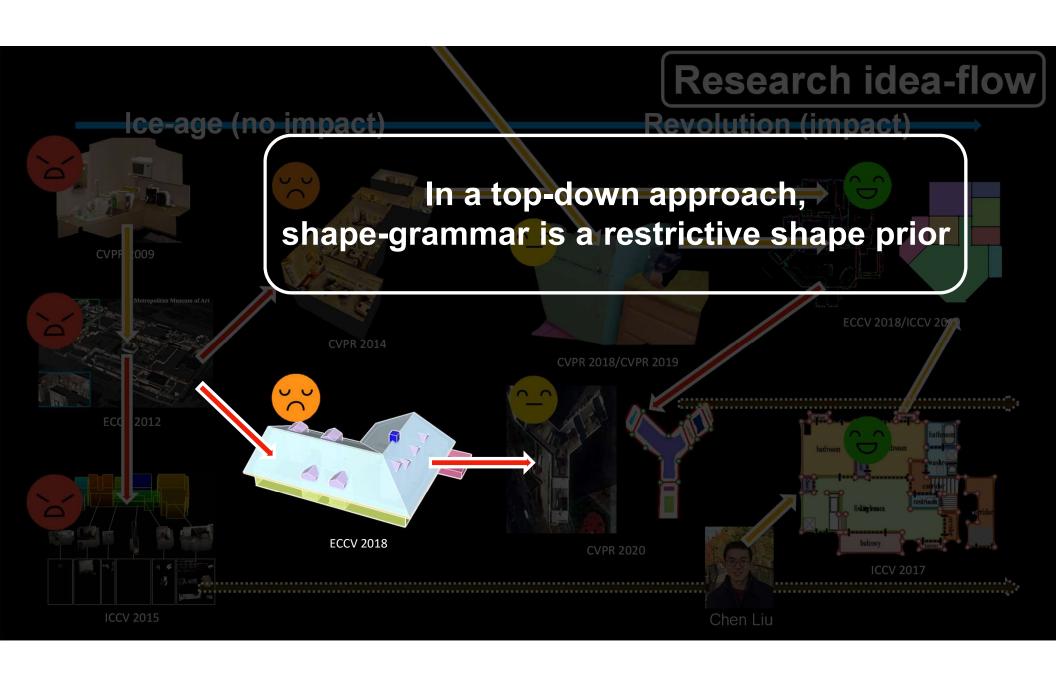
## Top-down: Region Detection



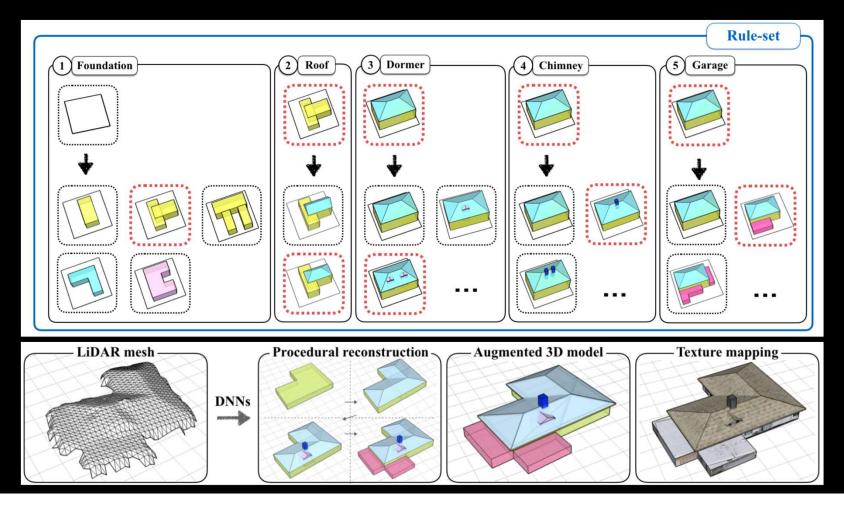






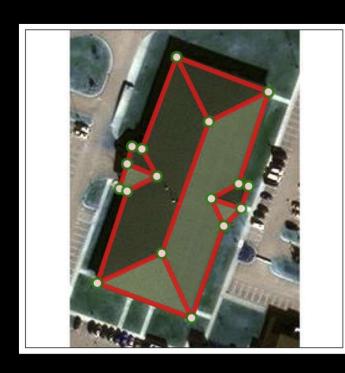


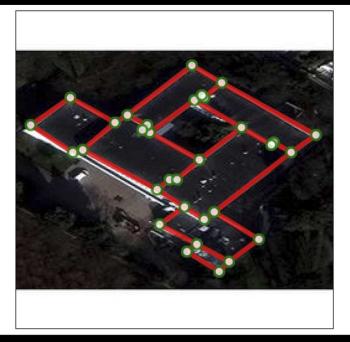
## Shape grammar as a shape prior



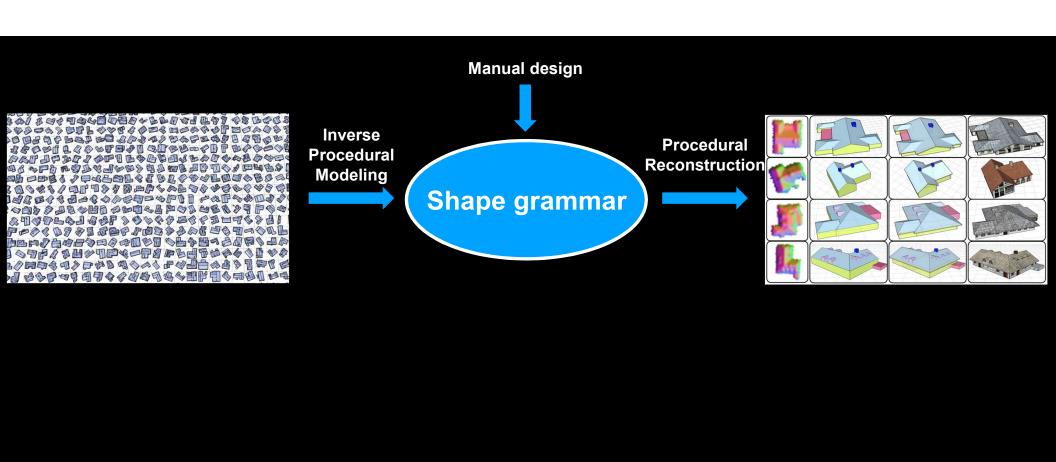


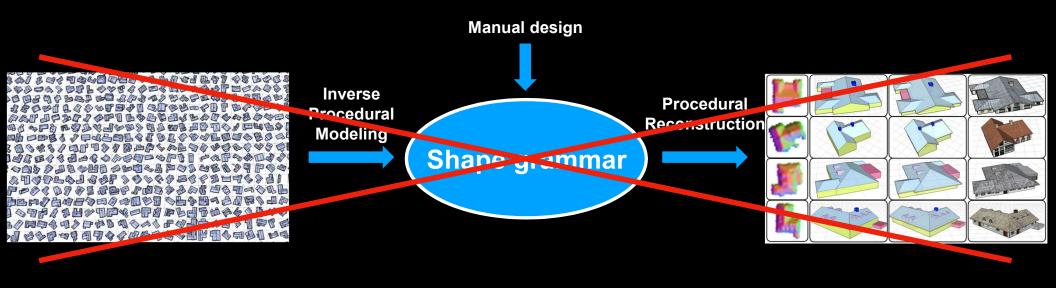
# Grammar cannot model complex buildings

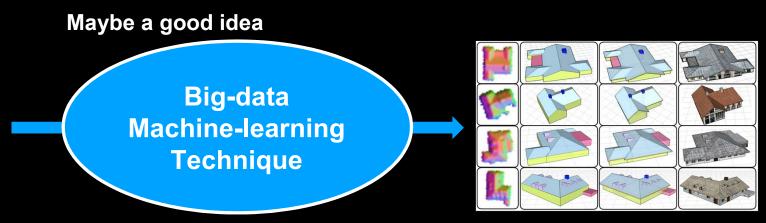


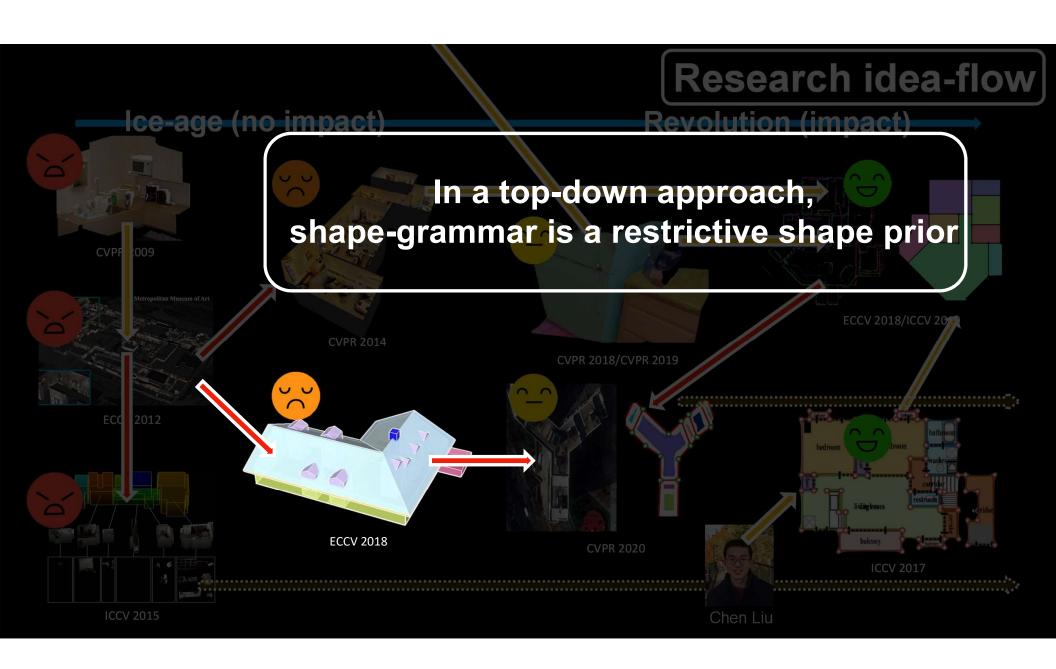


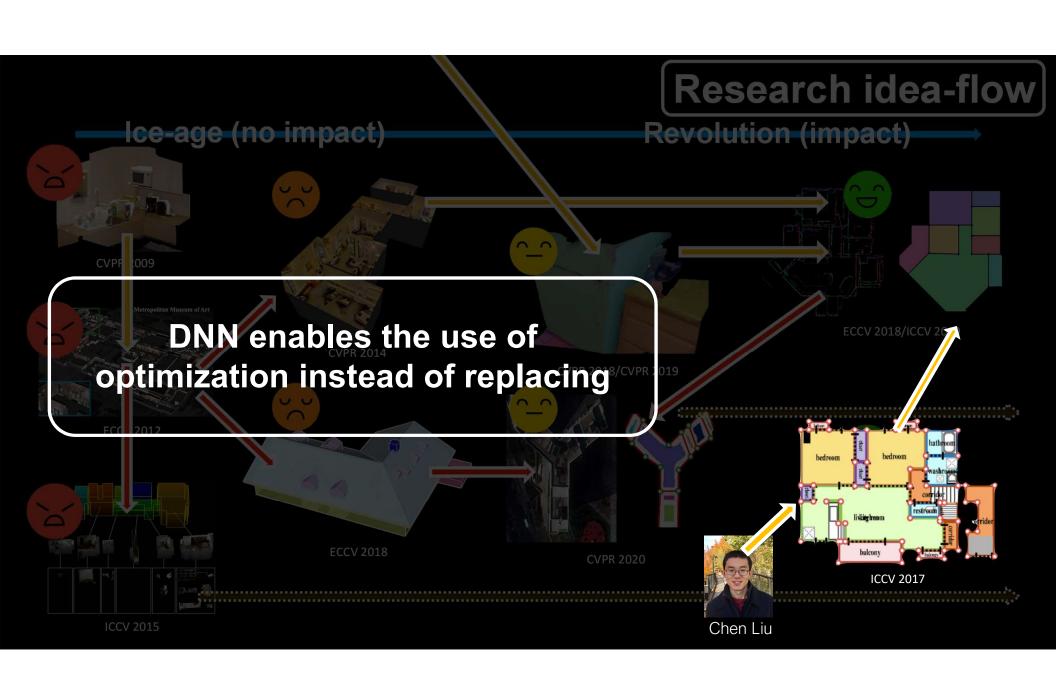












## Outdoor Architecture Vectorization

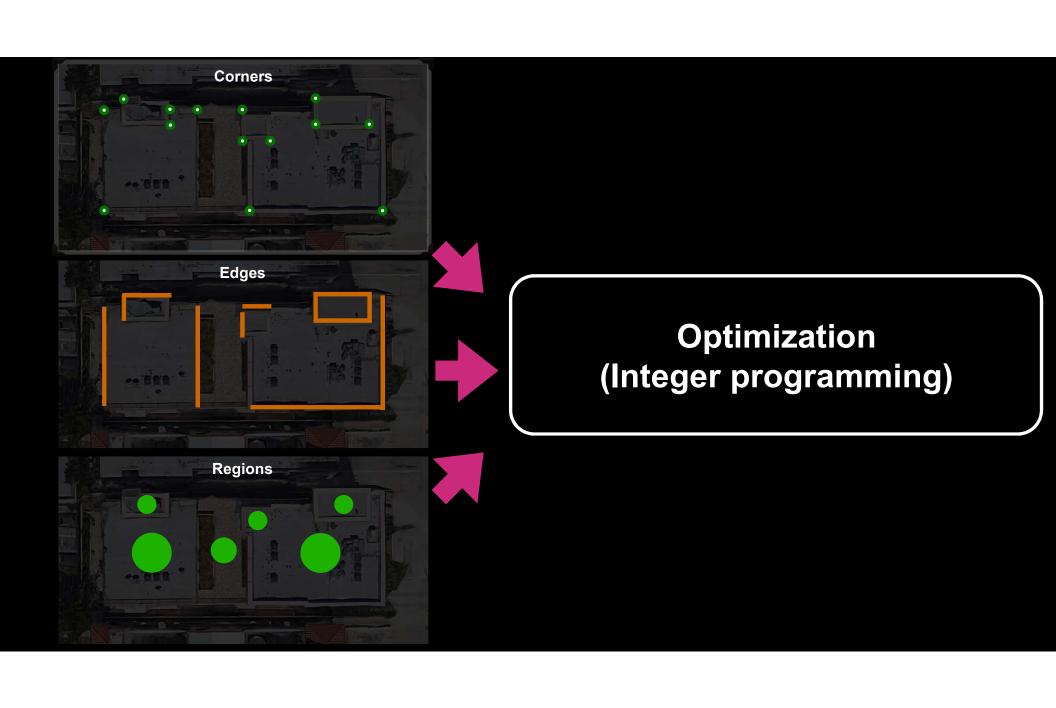
Google Maps - satellite (2D)



CAD model / Architect drawing







## DNN enables optimization instead of replacing

- DNN shrinks candidate pool
- DNN make energy landscape easy

	Scalability	Inference power
MRF	A few million vars	Pairwise Mostly submodular
ΙΡ	A few hundred vars	Higher-order Non-submodular

